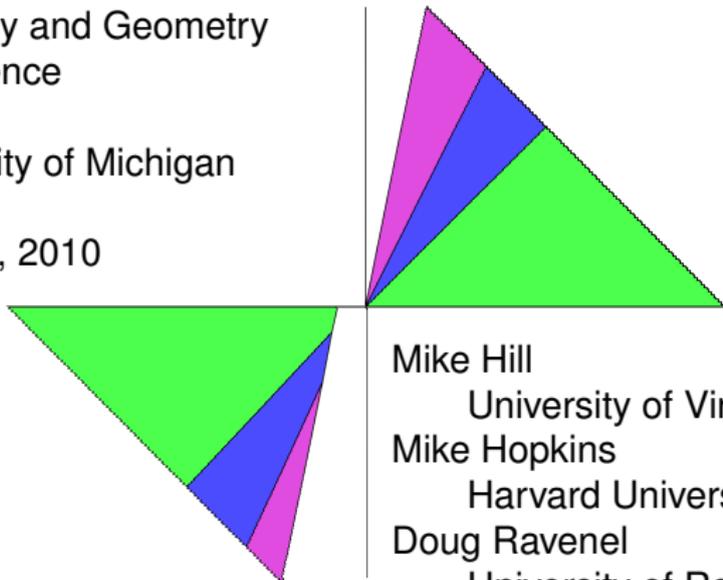


A solution to the Arf-Kervaire invariant problem

Eighth Annual
Graduate Student
Topology and Geometry
Conference

University of Michigan

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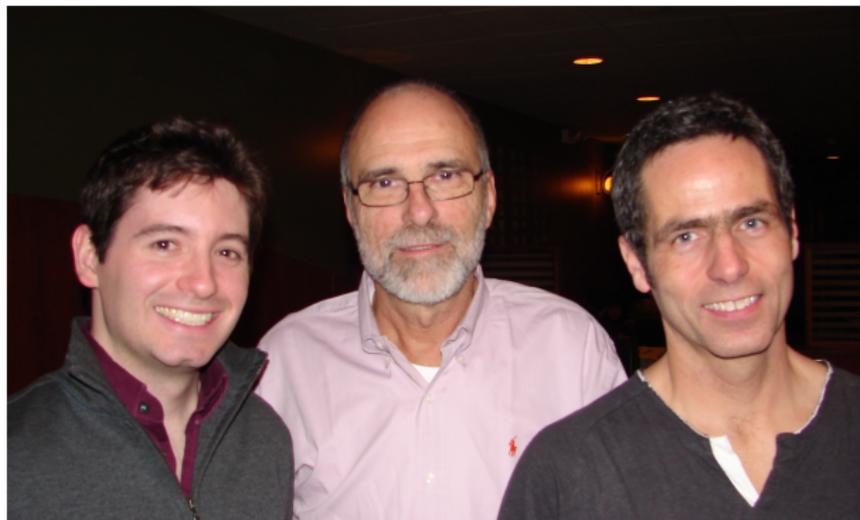


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Mike Hill, myself and Mike Hopkins
Photo taken by Bill Browder
February 11, 2010

Our main result

Our main theorem can be stated in three different but equivalent ways:

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Our main result

Our main theorem can be stated in three different but equivalent ways:

- **Manifold formulation:** It says that a certain geometrically defined invariant $\Phi(M)$ (the Arf-Kervaire invariant, to be defined later) on certain manifolds M is always zero.

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- **Stable homotopy theoretic formulation:** It says that certain long sought hypothetical maps between high dimensional spheres do not exist.

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The problem solved by our theorem is nearly 50 years old.

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The problem solved by our theorem is nearly 50 years old. There were several unsuccessful attempts to solve it in the 1970s.

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The problem solved by our theorem is nearly 50 years old. There were several unsuccessful attempts to solve it in the 1970s. They were all aimed at proving the **opposite** of what we have proved.

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Here is the stable homotopy theoretic formulation.

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Here is the stable homotopy theoretic formulation.

Main Theorem

The Arf-Kervaire elements $\theta_j \in \pi_{2^{j+1}-2+n}(S^n)$ for large n do not exist for $j \geq 7$.

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Main Theorem

The Arf-Kervaire elements $\theta_j \in \pi_{2^{j+1}-2+n}(S^n)$ for large n do not exist for $j \geq 7$.

Here $\pi_k(X)$ (for a positive integer k) denotes **the k th homotopy group of the topological space X** , the set of continuous maps to X from the k -sphere S^k , up to continuous deformation.

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Here $\pi_k(X)$ (for a positive integer k) denotes **the k th homotopy group of the topological space X** , the set of continuous maps to X from the k -sphere S^k , up to continuous deformation. This set has a natural group structure, which is abelian for $k > 1$.

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The θ_j in the theorem is the name given to a hypothetical map between spheres for which the Arf-Kervaire invariant is nontrivial.

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The θ_j in the theorem is the name given to a hypothetical map between spheres for which the Arf-Kervaire invariant is nontrivial. It follows from Browder's theorem of 1969 that such things can exist only in dimensions that are 2 less than a power of 2.

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Mark Mahowald

Some homotopy theorists, most notably Mahowald, speculated about what would happen if θ_j existed for all j .

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Mark Mahowald

Some homotopy theorists, most notably Mahowald, speculated about what would happen if θ_j existed for all j . They derived numerous consequences about homotopy groups of spheres. The possible nonexistence of the θ_j for large j was known as the **Doomsday Hypothesis**.

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After 1980, the problem faded into the background because it was thought to be too hard.

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After 1980, the problem faded into the background because it was thought to be too hard. Our proof is two giant steps away from anything that was attempted in the 70s.

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After 1980, the problem faded into the background because it was thought to be too hard. Our proof is two giant steps away from anything that was attempted in the 70s. We now know that the world of homotopy theory is very different from what they had envisioned then.

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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f : S^{n+k} \rightarrow S^n$ was

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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f : S^{n+k} \rightarrow S^n$ was

- Assume f is smooth.

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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f : S^{n+k} \rightarrow S^n$ was

- Assume f is smooth. We know that any such map is can be continuously deformed to a smooth one.

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Lev Pontryagin 1908-1988

Pontryagin's approach to maps $f : S^{n+k} \rightarrow S^n$ was

- Assume f is smooth. We know that any such map is can be continuously deformed to a smooth one.
- Pick a regular value $y \in S^n$.

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- Assume f is smooth. We know that any such map can be continuously deformed to a smooth one.
- Pick a regular value $y \in S^n$. Its inverse image will be a smooth k -manifold M in S^{n+k} .

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Pontryagin's approach to maps $f : S^{n+k} \rightarrow S^n$ was

- Assume f is smooth. We know that any such map can be continuously deformed to a smooth one.
- Pick a regular value $y \in S^n$. Its inverse image will be a smooth k -manifold M in S^{n+k} .
- By studying such manifolds, Pontryagin was able to deduce things about maps between spheres.

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Let D^n be the closure of an open ball around $y \in S^n$.

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Let D^n be the closure of an open ball around $y \in S^n$. If it is sufficiently small, then $V^{n+k} = f^{-1}(D^n) \subset S^{n+k}$ is an $(n+k)$ -manifold homeomorphic to $M \times D^n$ with boundary homeomorphic to $M \times S^{n-1}$.

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A local coordinate system around around y pulls back to one around M called a **framing**.

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A local coordinate system around around y pulls back to one around M called a **framing**.

There is a way to reverse this procedure. A framed manifold $M^k \subset S^{n+k}$ determines a map $f : S^{n+k} \rightarrow S^n$.

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To proceed further, we need to be more precise about what we mean by continuous deformation.

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To proceed further, we need to be more precise about what we mean by continuous deformation.

Two maps $f_1, f_2 : S^{n+k} \rightarrow S^n$ are **homotopic** if there is a continuous map $h : S^{n+k} \times [0, 1] \rightarrow S^n$ (called a **homotopy between f_1 and f_2**) such that

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$$h(x, 0) = f_1(x) \quad \text{and} \quad h(x, 1) = f_2(x).$$

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$$h(x, 0) = f_1(x) \quad \text{and} \quad h(x, 1) = f_2(x).$$

If $y \in S^n$ is a regular value of h , then $h^{-1}(y)$ is a framed $(k+1)$ -manifold $N \subset S^{n+k} \times [0, 1]$

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If $y \in S^n$ is a regular value of h , then $h^{-1}(y)$ is a framed $(k+1)$ -manifold $N \subset S^{n+k} \times [0, 1]$ whose boundary is the disjoint union of $M_1 = f_1^{-1}(y)$ and $M_2 = f_2^{-1}(y)$. This N is called a **framed cobordism** between M_1 and M_2 .

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Two maps $f_1, f_2 : S^{n+k} \rightarrow S^n$ are **homotopic** if there is a continuous map $h : S^{n+k} \times [0, 1] \rightarrow S^n$ (called a **homotopy between f_1 and f_2**) such that

$$h(x, 0) = f_1(x) \quad \text{and} \quad h(x, 1) = f_2(x).$$

If $y \in S^n$ is a regular value of h , then $h^{-1}(y)$ is a framed $(k+1)$ -manifold $N \subset S^{n+k} \times [0, 1]$ whose boundary is the disjoint union of $M_1 = f_1^{-1}(y)$ and $M_2 = f_2^{-1}(y)$. This N is called a **framed cobordism** between M_1 and M_2 . When it exists the two closed manifolds are said to be **framed cobordant**.

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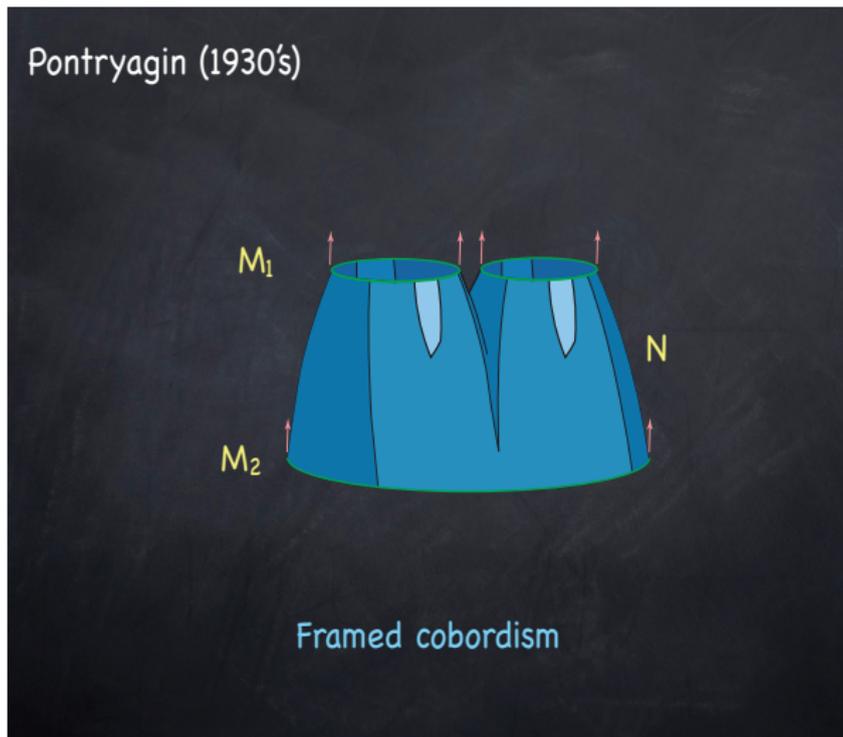
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Here is an example of a framed cobordism for $n = k = 1$.



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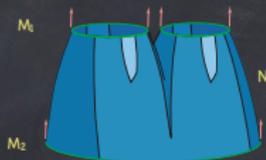
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Pontryagin (1930's)



$$\Omega_k := \{\text{stably framed } k\text{-manifolds}\} / \text{cobordism}$$

Theorem: The above construction gives a bijection

$$\pi_{n+k}(S^n) \approx \Omega_k$$

where

$$\pi_{n+k}(S^n) := \{\text{maps } S^{n+k} \rightarrow S^n\} / \text{homotopy}$$

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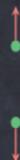
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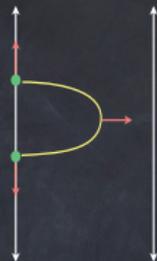
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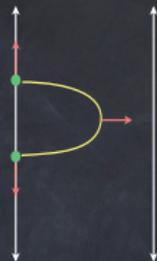
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$$\pi_n(S^n) = \mathbb{Z}$$

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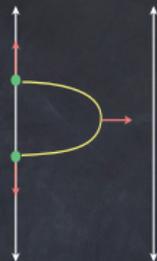
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$$\pi_n(S^n) = \mathbb{Z}$$

(the degree)

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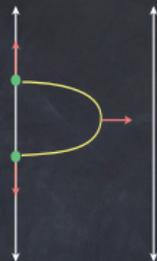
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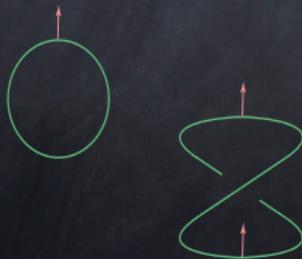
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$$\pi_n(S^n) = \mathbb{Z}$$

(the degree)

$k=1$



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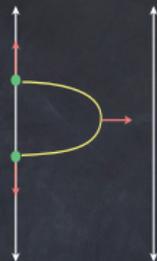
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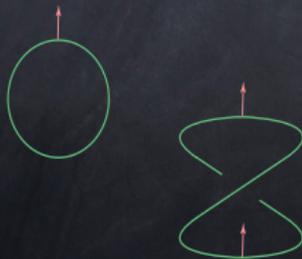
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$$\pi_n(S^n) = \mathbb{Z}$$

(the degree)

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$$\pi_{n+1}(S^n) = \mathbb{Z}/2$$

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$k=2$ genus $M = 0 \Rightarrow M$ is a boundary

(since S^2 bounds a disk and
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Pontryagin (1930's)

$k=2$ genus $M = 0 \Rightarrow M$ is a boundary

(since S^2 bounds a disk and
 $\pi_2(\mathrm{GL}_n(\mathbf{R}))=0$)

Suppose the genus of M is
greater than 0.

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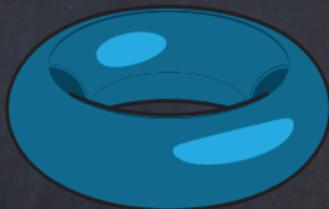
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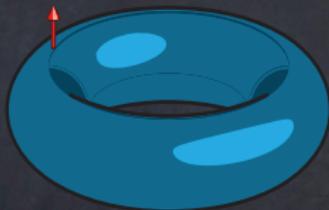
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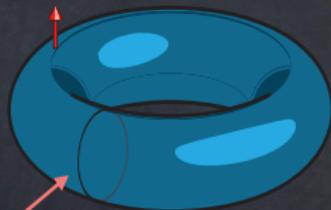
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choose an
embedded arc

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choose an
embedded arc

cut the surface open
and glue in disks

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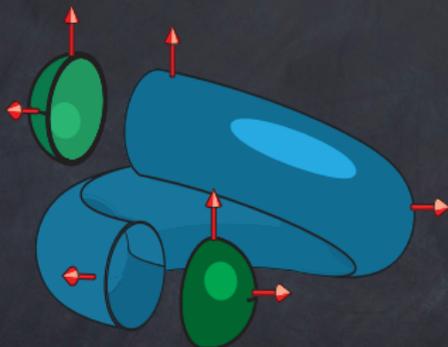
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framed surgery

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Obstruction: $\varphi : H_1(M; \mathbb{Z}/2) \rightarrow \mathbb{Z}/2$

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Obstruction: $\varphi : H_1(M; \mathbb{Z}/2) \rightarrow \mathbb{Z}/2$

Argument: Since the dimension of $H_1(M; \mathbb{Z}/2)$ is even, there is always a non-zero element in the kernel of φ , and so surgery can be performed.

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Obstruction: $\varphi : H_1(M; \mathbb{Z}/2) \rightarrow \mathbb{Z}/2$

Argument: Since the dimension of $H_1(M; \mathbb{Z}/2)$ is even, there is always a non-zero element in the kernel of φ , and so surgery can be performed.

Conclusion: $\Omega_2 = \pi_{n+2}(S^n) = 0$.

Pontryagin's mistake for $k = 2$

The map $\varphi : H_1(M; \mathbf{Z}/2) \rightarrow \mathbf{Z}/2$ is **not** a homomorphism!

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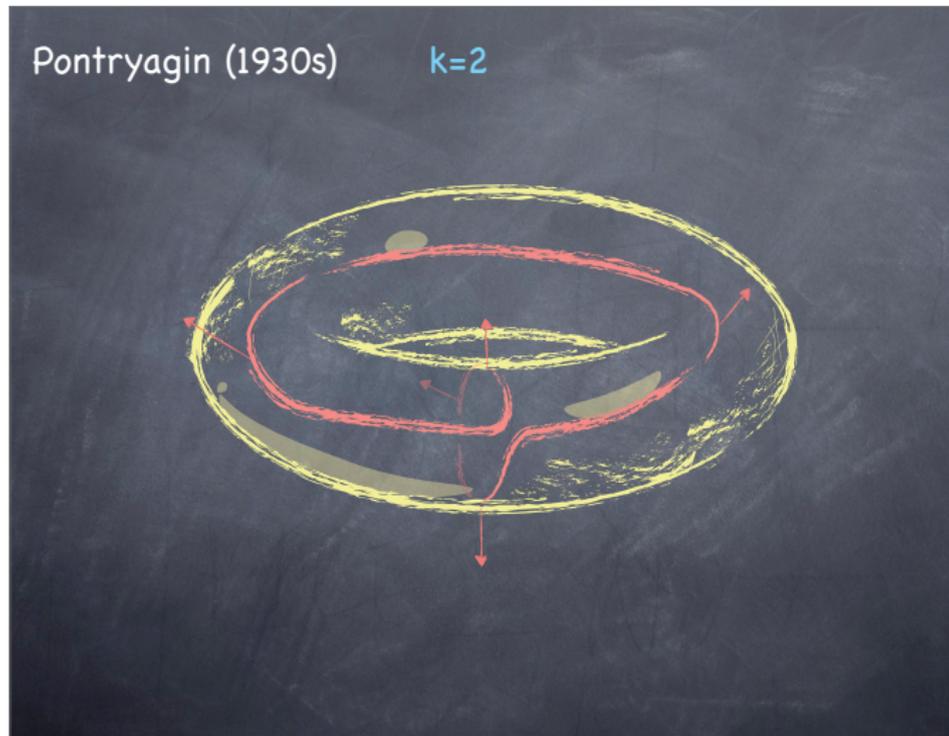
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Tuesday, April 21, 2009

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The Arf invariant of a quadratic form in characteristic 2

Let λ be a nonsingular anti-symmetric bilinear form on a free abelian group H of rank $2n$ with mod 2 reduction \overline{H} .

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The Arf invariant of a quadratic form in characteristic 2

Let λ be a nonsingular anti-symmetric bilinear form on a free abelian group H of rank $2n$ with mod 2 reduction \overline{H} . It is known that \overline{H} has a basis of the form $\{a_i, b_i : 1 \leq i \leq n\}$ with

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$$\lambda(a_i, a_{i'}) = 0 \quad \lambda(b_j, b_{j'}) = 0 \quad \text{and} \quad \lambda(a_i, b_j) = \delta_{i,j}.$$

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A quadratic refinement of λ is a map $q : \bar{H} \rightarrow \mathbf{Z}/2$ satisfying

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A quadratic refinement of λ is a map $q : \bar{H} \rightarrow \mathbf{Z}/2$ satisfying

$$q(x + y) = q(x) + q(y) + \lambda(x, y)$$

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A quadratic refinement of λ is a map $q : \bar{H} \rightarrow \mathbf{Z}/2$ satisfying

$$q(x + y) = q(x) + q(y) + \lambda(x, y)$$

Its Arf invariant is

$$\text{Arf}(q) = \sum_{i=1}^n q(a_i)q(b_i) \in \mathbf{Z}/2.$$

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A quadratic refinement of λ is a map $q : \bar{H} \rightarrow \mathbf{Z}/2$ satisfying

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Its Arf invariant is

$$\text{Arf}(q) = \sum_{i=1}^n q(a_i)q(b_i) \in \mathbf{Z}/2.$$

In 1941 Arf proved that this invariant (along with the number n) determines the isomorphism type of q .

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Money talks: Arf's definition republished in 2009



Cahit Arf 1910-1997

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The Kervaire invariant of a framed $(4m + 2)$ -manifold

Let M be a $2m$ -connected smooth closed framed manifold of dimension $4m + 2$.

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Let M be a $2m$ -connected smooth closed framed manifold of dimension $4m + 2$. Let $H = H_{2m+1}(M; \mathbf{Z})$, the homology group in the middle dimension.

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Let M be a $2m$ -connected smooth closed framed manifold of dimension $4m + 2$. Let $H = H_{2m+1}(M; \mathbf{Z})$, the homology group in the middle dimension. Each $x \in H$ is represented by an immersion $i_x : S^{2m+1} \looparrowright M$ with a stably trivialized normal bundle.

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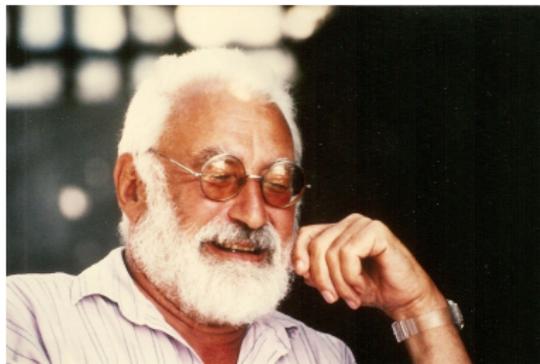
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Michel Kervaire 1927-2007

Kervaire defined a quadratic refinement q on its mod 2 reduction in terms of the trivialization of each sphere's normal bundle.

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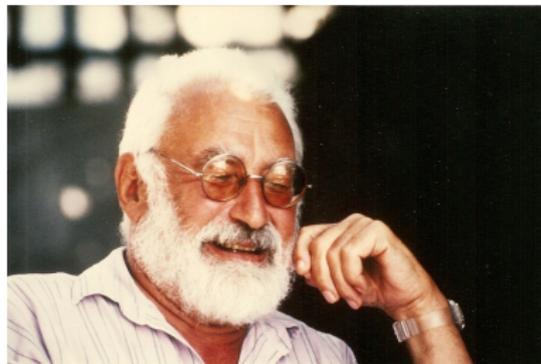
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The Kervaire invariant of a framed $(4m + 2)$ -manifold

Let M be a $2m$ -connected smooth closed framed manifold of dimension $4m + 2$. Let $H = H_{2m+1}(M; \mathbf{Z})$, the homology group in the middle dimension. Each $x \in H$ is represented by an immersion $i_x : S^{2m+1} \looparrowright M$ with a stably trivialized normal bundle. H has an antisymmetric bilinear form λ defined in terms of intersection numbers.



Michel Kervaire 1927-2007

Kervaire defined a quadratic refinement q on its mod 2 reduction in terms of the trivialization of each sphere's normal bundle. The **Kervaire invariant** $\Phi(M)$ is defined to be the Arf invariant of q .

A solution to the Arf-Kervaire invariant problem

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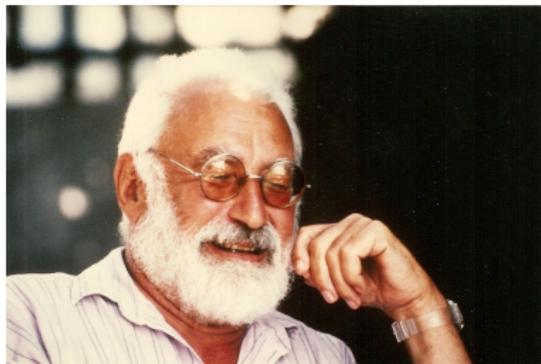
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The Kervaire invariant of a framed $(4m + 2)$ -manifold

Let M be a $2m$ -connected smooth closed framed manifold of dimension $4m + 2$. Let $H = H_{2m+1}(M; \mathbf{Z})$, the homology group in the middle dimension. Each $x \in H$ is represented by an immersion $i_x : S^{2m+1} \looparrowright M$ with a stably trivialized normal bundle. H has an antisymmetric bilinear form λ defined in terms of intersection numbers.



Michel Kervaire 1927-2007

Kervaire defined a quadratic refinement q on its mod 2 reduction in terms of the trivialization of each sphere's normal bundle. The **Kervaire invariant** $\Phi(M)$ is defined to be the Arf invariant of q .

For $m = 0$, **Kervaire's q** coincides with Pontryagin's φ .

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What can we say about $\Phi(M)$?

- For $m = 0$ there is a framing on the torus $S^1 \times S^1 \subset \mathbf{R}^4$ with nontrivial Kervaire invariant.

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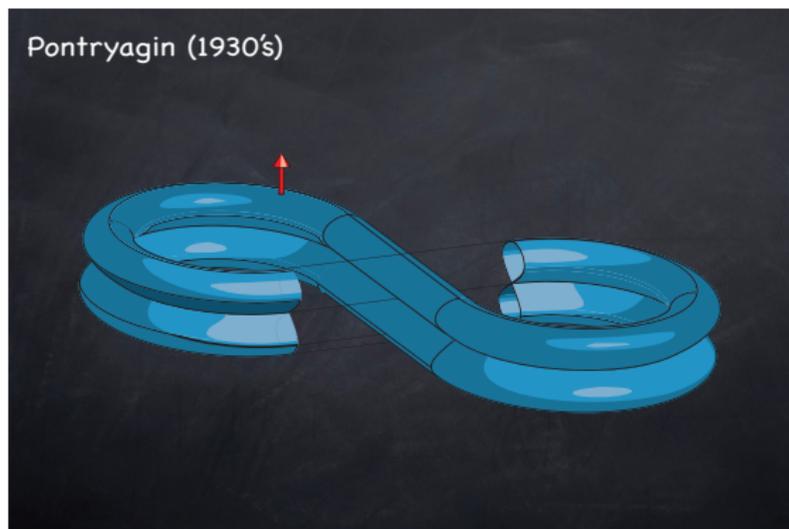
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- Kervaire (1960) showed it must vanish when $m = 2$.

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- Kervaire (1960) showed it must vanish when $m = 2$. This enabled him to construct the first example of a topological manifold (of dimension 10) without a smooth structure.

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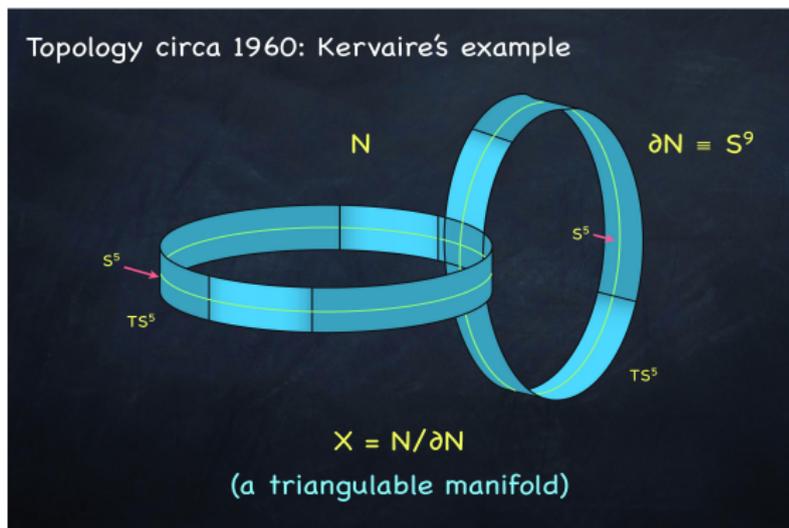
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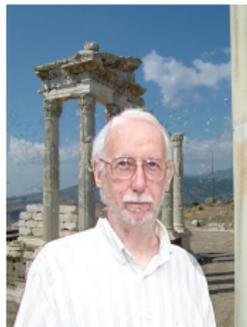
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Ed Brown



Frank Peterson
1930-2000

Brown-Peterson (1966) showed that it vanishes for all positive even m .

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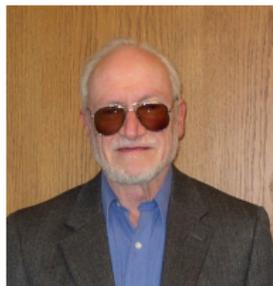
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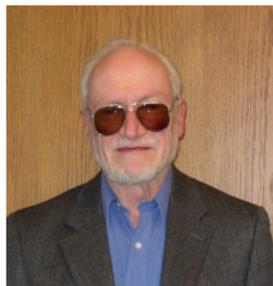
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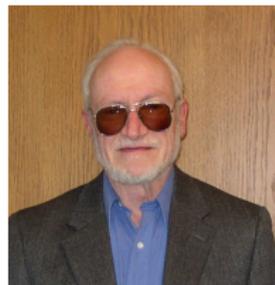
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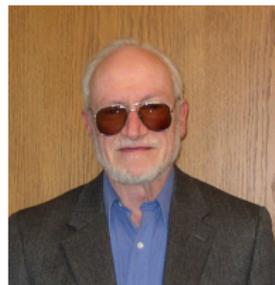
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- θ_j is known to exist for $1 \leq j \leq 5$, i.e., in dimensions 2, 6, 14, 30 and 62.

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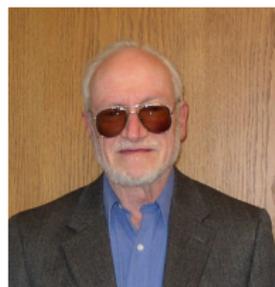
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- θ_j is known to exist for $1 \leq j \leq 5$, i.e., in dimensions 2, 6, 14, 30 and 62.
- In the decade following Browder's theorem, many topologists tried **without success** to construct framed manifolds with nontrivial Kervaire invariant in **all** dimensions 2 less than a power of 2.

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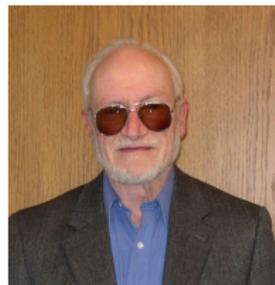
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Adams spectral sequence formulation. We now know that the h_j^2 for $j \geq 7$ are not permanent cycles, so they have to support nontrivial differentials.

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Unstable homotopy theoretic formulation.

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Our method of proof offers a new tool, **the slice spectral sequence**, for studying the stable homotopy groups of spheres.

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- We use methods of stable homotopy theory, which means we use spectra instead of topological spaces.

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Spectra are to spaces as integers are to natural numbers.

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In particular, recall that a space X has a homotopy group $\pi_k(X)$ for each positive integer k .



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In particular, recall that a space X has a homotopy group $\pi_k(X)$ for each positive integer k . A spectrum X has an abelian homotopy group $\pi_k(X)$ **defined for every integer k .**

For the sphere spectrum S^0 , $\pi_k(S^0)$ is the usual homotopy group $\pi_{n+k}(S^n)$ for $n > k + 1$.



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Our proof has several ingredients.

- We use methods of stable homotopy theory, which means we use spectra instead of topological spaces. The definition of these would take us too far afield, so instead we offer a slogan:

Spectra are to spaces as integers are to natural numbers.

In particular, recall that a space X has a homotopy group $\pi_k(X)$ for each positive integer k . A spectrum X has an abelian homotopy group $\pi_k(X)$ **defined for every integer k .**

For the sphere spectrum S^0 , $\pi_k(S^0)$ is the usual homotopy group $\pi_{n+k}(S^n)$ for $n > k + 1$. The hypothetical θ_j is an element of this group for $k = 2^{j+1} - 2$.

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More ingredients of our proof:

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Mike Hopkins
Doug Ravenel



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Ingredients of the proof (continued)

More ingredients of our proof:

- We use complex cobordism theory.

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More ingredients of our proof:

- We use complex cobordism theory. This is a branch of algebraic topology having deep connections with algebraic geometry and number theory.

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More ingredients of our proof:

- We use complex cobordism theory. This is a branch of algebraic topology having deep connections with algebraic geometry and number theory. It includes some highly developed computational techniques that began with work by Milnor, Novikov and Quillen in the 60s.

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More ingredients of our proof:

- We use complex cobordism theory. This is a branch of algebraic topology having deep connections with algebraic geometry and number theory. It includes some highly developed computational techniques that began with work by Milnor, Novikov and Quillen in the 60s. A pivotal tool in the subject is the theory of formal group laws.



John Milnor



Sergei Novikov



Dan Quillen

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Ingredients of the proof (continued)

More ingredients of our proof:

- We also make use of newer less familiar methods from equivariant stable homotopy theory.

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Ingredients of the proof (continued)

More ingredients of our proof:

- We also make use of newer less familiar methods from equivariant stable homotopy theory. This means there is a finite group G (a cyclic 2-group) acting on all spaces in sight, and all maps are required to commute with these actions.

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Ingredients of the proof (continued)

More ingredients of our proof:

- We also make use of newer less familiar methods from equivariant stable homotopy theory. This means there is a finite group G (a cyclic 2-group) acting on all spaces in sight, and all maps are required to commute with these actions. When we pass to spectra, we get homotopy groups indexed not just by the integers \mathbf{Z} , but by $RO(G)$, the real representation ring of G .

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More ingredients of our proof:

- We also make use of newer less familiar methods from equivariant stable homotopy theory. This means there is a finite group G (a cyclic 2-group) acting on all spaces in sight, and all maps are required to commute with these actions. When we pass to spectra, we get homotopy groups indexed not just by the integers \mathbf{Z} , but by $RO(G)$, the real representation ring of G . Our calculations make use of this richer structure.



Peter May



John Greenlees



Gauance Lewis
1949-2006

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The spectrum Ω

We will produce a map $S^0 \rightarrow \Omega$, where Ω is a nonconnective spectrum (meaning that it has nontrivial homotopy groups in arbitrarily large negative dimensions) with the following properties.

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The spectrum Ω

We will produce a map $S^0 \rightarrow \Omega$, where Ω is a nonconnective spectrum (meaning that it has nontrivial homotopy groups in arbitrarily large negative dimensions) with the following properties.

- (i) **Detection Theorem.** It has an Adams-Novikov spectral sequence (which is a device for calculating homotopy groups) in which the image of each θ_j is nontrivial.

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- (i) **Detection Theorem.** It has an Adams-Novikov spectral sequence (which is a device for calculating homotopy groups) in which the image of each θ_j is nontrivial. This means that if θ_j exists, we will see its image in $\pi_*(\Omega)$.

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- (i) **Detection Theorem.** It has an Adams-Novikov spectral sequence (which is a device for calculating homotopy groups) in which the image of each θ_j is nontrivial. This means that if θ_j exists, we will see its image in $\pi_*(\Omega)$.
- (ii) **Periodicity Theorem.** It is 256-periodic, meaning that $\pi_k(\Omega)$ depends only on the reduction of k modulo 256.

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- (ii) **Periodicity Theorem.** It is 256-periodic, meaning that $\pi_k(\Omega)$ depends only on the reduction of k modulo 256.
- (iii) **Gap Theorem.** $\pi_k(\Omega) = 0$ for $-4 < k < 0$.



We will produce a map $S^0 \rightarrow \Omega$, where Ω is a nonconnective spectrum (meaning that it has nontrivial homotopy groups in arbitrarily large negative dimensions) with the following properties.

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- (ii) **Periodicity Theorem.** It is 256-periodic, meaning that $\pi_k(\Omega)$ depends only on the reduction of k modulo 256.
- (iii) **Gap Theorem.** $\pi_k(\Omega) = 0$ for $-4 < k < 0$. This property is our zinger. Its proof involves a new tool we call the slice spectral sequence.

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Here again are the properties of Ω

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Here again are the properties of Ω

- (i) **Detection Theorem.** If θ_j exists, it has nontrivial image in $\pi_*(\Omega)$.
- (ii) **Periodicity Theorem.** $\pi_k(\Omega)$ depends only on the reduction of k modulo 256.
- (iii) **Gap Theorem.** $\pi_{-2}(\Omega) = 0$.

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Here again are the properties of Ω

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- (ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

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- (ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

If $\theta_7 \in \pi_{254}(S^0)$ exists, (i) implies it has a nontrivial image in this group, so it cannot exist.

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 - (iii) **Gap Theorem.** $\pi_{-2}(\Omega) = 0$.
- (ii) and (iii) imply that $\pi_{254}(\Omega) = 0$.

If $\theta_7 \in \pi_{254}(S^0)$ exists, (i) implies it has a nontrivial image in this group, so it cannot exist. The argument for θ_j for larger j is similar, since $|\theta_j| = 2^{j+1} - 2 \equiv -2 \pmod{256}$ for $j \geq 7$.

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Our spectrum Ω will be the fixed point spectrum for the action of C_8 (the cyclic group of order 8) on an equivariant spectrum $\tilde{\Omega}$.

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To construct it we start with the complex cobordism spectrum MU .

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Our spectrum Ω will be the fixed point spectrum for the action of C_8 (the cyclic group of order 8) on an equivariant spectrum $\tilde{\Omega}$.

To construct it we start with the complex cobordism spectrum MU . It can be thought of as the set of complex points of an algebraic variety defined over the real numbers.

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To construct it we start with the complex cobordism spectrum MU . It can be thought of as the set of complex points of an algebraic variety defined over the real numbers. This means that it has an action of C_2 defined by complex conjugation.

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To construct it we start with the complex cobordism spectrum MU . It can be thought of as the set of complex points of an algebraic variety defined over the real numbers. This means that it has an action of C_2 defined by complex conjugation. The fixed point set of this action is the set of real points, known to topologists as MO , the unoriented cobordism spectrum.

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Peter Landweber

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Peter Landweber



Shoro Araki
1930–2005

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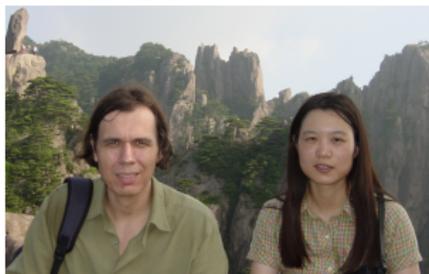
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Some people who have studied MU as a C_2 -spectrum:



Peter Landweber



Igor Kriz and Po Hu



Shoro Araki
1930–2005

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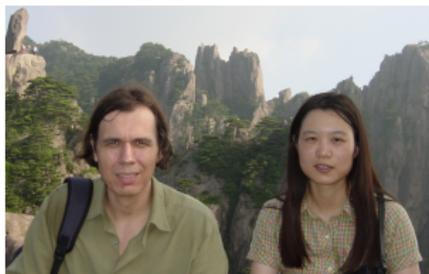
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Some people who have studied MU as a C_2 -spectrum:



Peter Landweber



Igor Kriz and Po Hu



Shoro Araki
1930–2005



Nitu Kitchloo



Steve Wilson

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To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum X acted on by a group H to one acted on by a larger group G containing H as a subgroup.

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How we construct Ω (continued)

To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum X acted on by a group H to one acted on by a larger group G containing H as a subgroup. Let

$$Y = \text{Map}_H(G, X),$$

the space (or spectrum) of H -equivariant maps from G to X .

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$$Y = \text{Map}_H(G, X),$$

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$$Y = \text{Map}_H(G, X),$$

the space (or spectrum) of H -equivariant maps from G to X . Here the action of H on G is by right multiplication, and the resulting object has an action of G by left multiplication. As a set, $Y = X^{|G/H|}$, the $|G/H|$ -fold Cartesian power of X .

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In particular we get a C_8 -spectrum

$$MU^{(4)} = \text{Map}_{C_2}(C_8, MU).$$

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To get a C_8 -spectrum, we use the following general construction for getting from a space or spectrum X acted on by a group H to one acted on by a larger group G containing H as a subgroup. Let

$$Y = \text{Map}_H(G, X),$$

the space (or spectrum) of H -equivariant maps from G to X . Here the action of H on G is by right multiplication, and the resulting object has an action of G by left multiplication. As a set, $Y = X^{|G/H|}$, the $|G/H|$ -fold Cartesian power of X . A general element of G permutes these factors, each of which is left invariant by the subgroup H .

In particular we get a C_8 -spectrum

$$MU^{(4)} = \text{Map}_{C_2}(C_8, MU).$$

This spectrum is not periodic, but it has a close relative $\tilde{\Omega}$ which is.

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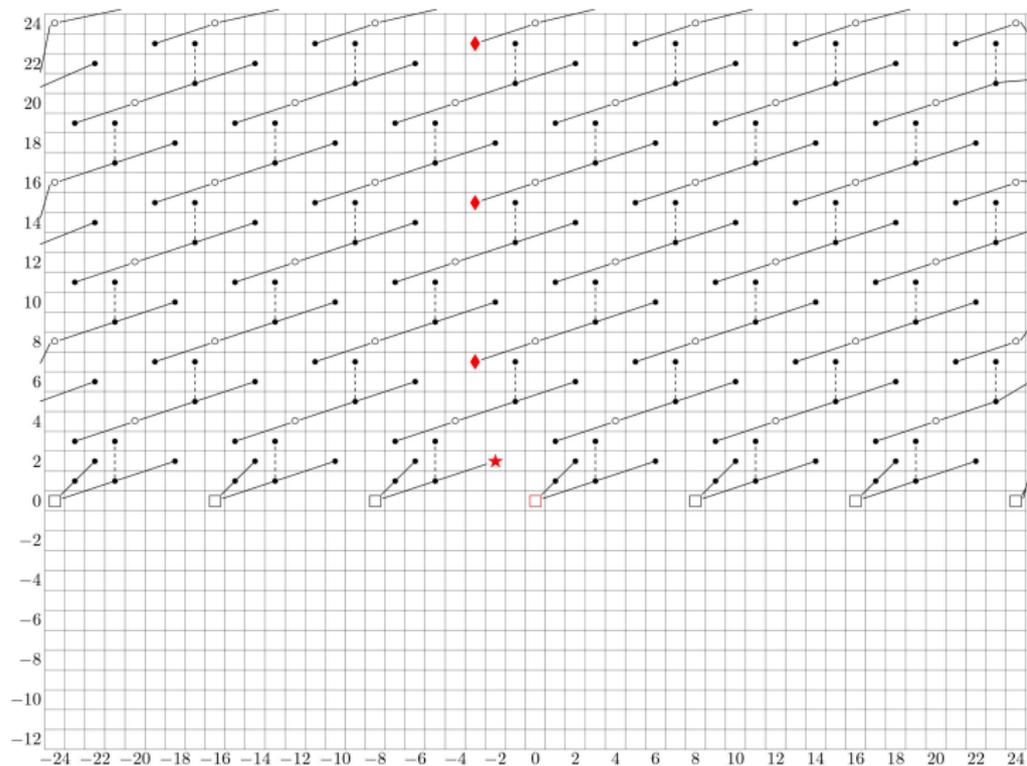
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The slice spectral sequence

A homotopy fixed point spectral sequence



A solution to the
Arf-Kervaire invariant
problem

Mike Hill
Mike Hopkins
Doug Ravenel



Background and
history

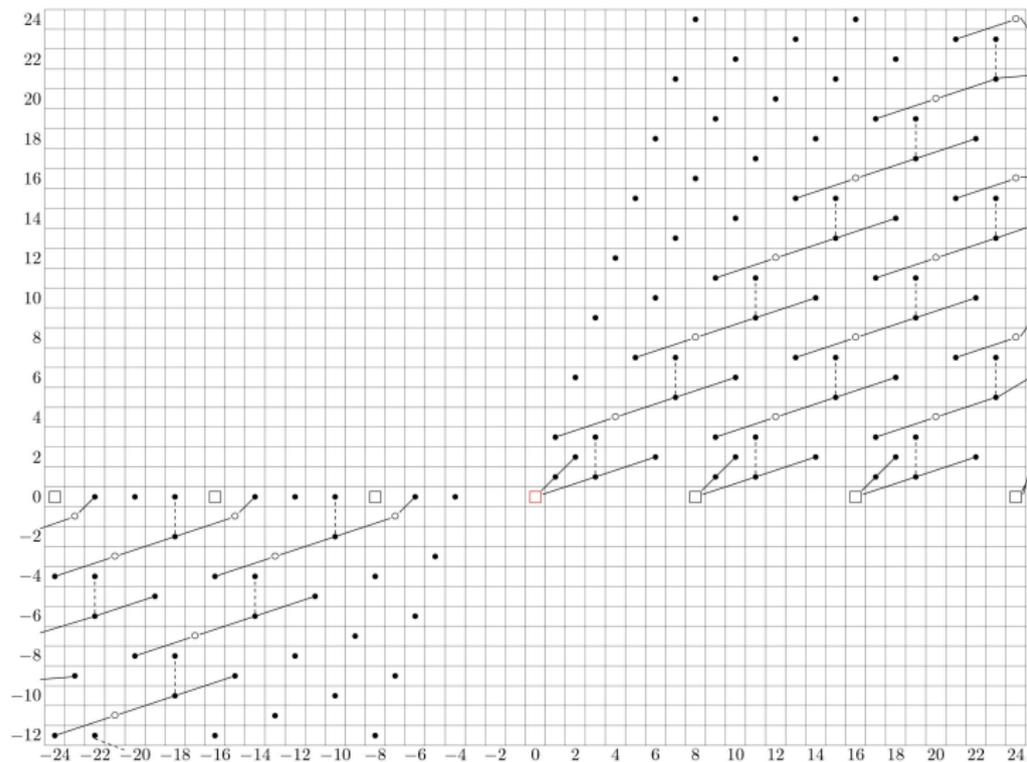
Our main result
Pontryagin's early work
The Arf-Kervaire
formulation
Questions raised by our
theorem

Our strategy

Ingredients of the proof
The spectrum Ω
How we construct Ω

The slice spectral sequence

The corresponding slice spectral sequence



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The slice spectral sequence